

Pyomo – Optimierung mit Python

Strommarkt-TechTalk – Berlin – 20.02.2015

Philipp Hanemann

Professur für Energiemanagement und Nachhaltigkeit
Institut für Infrastruktur und Ressourcenmanagement - IIRM
Universität Leipzig



Warum Python?

- Open source
 - Vollwertige Programmiersprache (high level)
 - Vektorrechnung (Numpy, Scipy)
 - Zeitreihen (Pandas)
 - **Optimierung** (cvx-opt, Pyomo)
 - viele andere Libraries
 - große Community → dynamische Entwicklung
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Ein Tool für alles

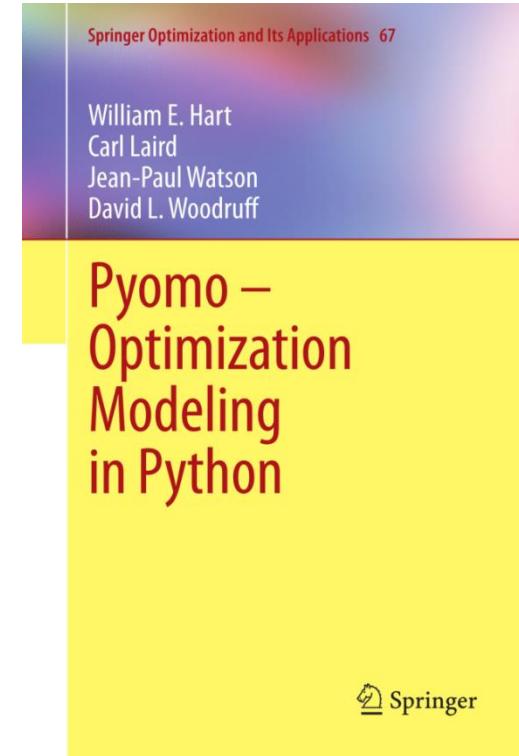
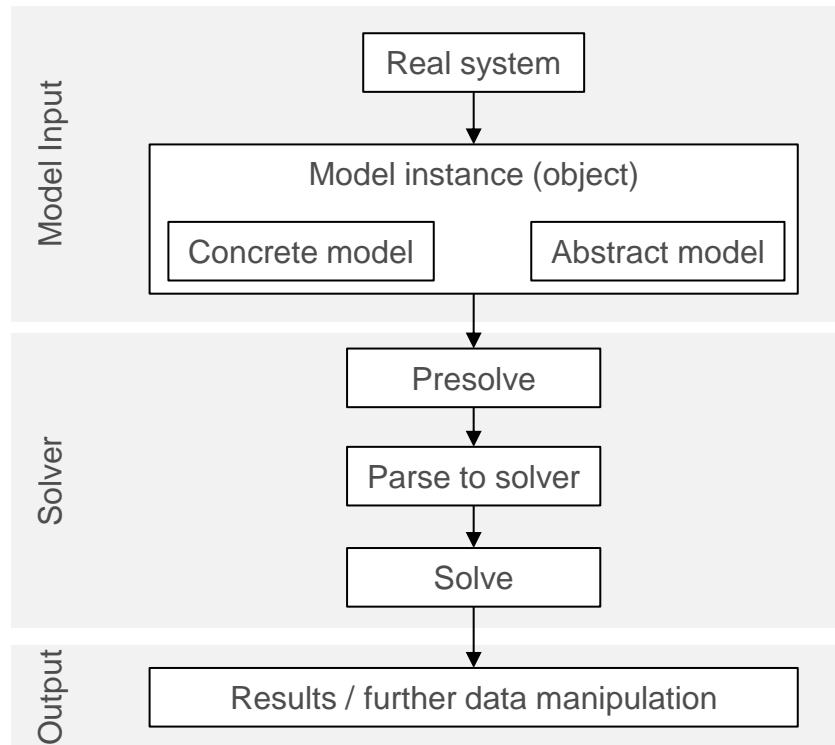


Pyomo (<http://www.pyomo.org/> - new 😊)

„The goal of Pyomo is to provide a platform for expressing optimization models that supports the central ideas of modern **algebraic modeling languages** within a framework that promotes *flexibility, extensibility, portability, and maintainability*.“

Latest version: 4.0 (22nd January 2015)

In Python everything is an object!!!



Concrete Model

Problem		
max	$3x_1 + 5x_2$	Pyomo library
s.t.:	$x_1 \leq 4$	Model object
	$x_2 \leq 6$	specification
	$3x_1 + 2x_2 \leq 18$	
	$x_1 \geq 0, x_2 \geq 0$	
	<pre>from coopr.pyomo import * from coopr.opt import SolverFactory m = ConcreteModel() m.x1 = Var() m.x2 = Var() m.obj = Objective(expr = 3*m.x1 + 5*m.x2, sense = maximize) m.con1 = Constraint(expr = 1*m.x1 + 0*m.x2 <= 4) m.con2 = Constraint(expr = 0*m.x1 + 1*m.x2 <= 6) m.con3 = Constraint(expr = 3*m.x1 + 2*m.x2 <= 18) m.con4 = Constraint(expr = m.x1 >= 0) m.con5 = Constraint(expr = m.x2 >= 0)</pre>	
	<pre>inst = m.create()</pre>	Model instance
	<pre>opt = SolverFactory("glpk") results = opt.solve(inst)</pre>	Solver specification Model solve

Abstract Model

Problem

$$\begin{aligned} \max \quad & 3x_1 + 5x_2 \\ \text{s.t.:} \quad & x_1 \leq 4 \\ & x_2 \leq 6 \\ & 3x_1 + 2x_2 \leq 18 \\ & x_1 \geq 0, x_2 \geq 0 \end{aligned}$$

$\max\{c^T x \mid Ax \leq b, x \geq 0\}$
with $A \in \mathbb{R}^{m,n}, b \in \mathbb{R}^m, c \in \mathbb{R}^n$

```
from coopr.pyomo import *
from coopr.opt import SolverFactory

#instantiating a m
m = AbstractModel()
m.V = Set()
m.R = Set()
m.c = Param(m.V)
m.a = Param(m.R, m.V)
m.b = Param(m.R)
m.x = Var(m.V, within = NonNegativeReals)

def obj_rule(m):
    return sum(m.c[i]*m.x[i] for i in m.V)
m.obj = Objective(rule=obj_rule, sense = maximize)

def con_rule(m, r):
    return sum(m.a[r,i] * m.x[i] for i in m.V) <= m.b[r]
m.con = Constraint(m.R, rule=con_rule)

instance = m.create('lp_1_abstract_input.dat')

opt = SolverFactory("glpk")
results = opt.solve(instance)
```

Sets: V columns, R rows

Parameters for: c, A, b

$obj = \sum_{i \in V} c_i * x_i$

$\sum_{i \in V} a_{i,r} * x_i \leq b_r \quad \forall r \in R$

Input data

Kontakt

Philipp Hanemann

Professur für Energiemanagement und Nachhaltigkeit

Wirtschaftswissenschaftliche Fakultät

Universität Leipzig

Grimmaische Str. 12

D-04109 Leipzig

Tel.: 0341/97 33858

philipp.hanemann@uni-leipzig.de

www.wifa.uni-leipzig.de/iirm

